

#### Problem 4:



$$\vec{F}_2 = -P \hat{j}$$

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$$\vec{M}_2$$

$$\vec{r}_1 = 6a \hat{i} - 6a \hat{k}$$

$$\vec{r}_2 = 16a \hat{i} + 8a \hat{k}$$

$$\sum \vec{F} = \vec{0} = -F_x \hat{i} + V_y \hat{j} + V_z \hat{k} + P \hat{j} - P \hat{j}$$

$F_x = 0$   
 $V_z = 0$   
 $V_y = 0$   
 $V_y + P - P = 0$

$$\sum \vec{M} = \vec{0} = -T_x \hat{i} + M_y \hat{j} + M_z \hat{k} + \vec{r}_1 \times \vec{F}_1 + \vec{r}_2 \times \vec{F}_2$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 16a & 0 & -6a \\ 0 & P & 0 \end{vmatrix}$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 16a & 0 & 8a \\ 0 & -P & 0 \end{vmatrix}$$

$$\begin{aligned} & \hat{i} (0 \times 0 - P(-6a)) \\ & - \hat{j} (16a \times 0 - 0 \times (-6a)) \\ & + \hat{k} (16a \cdot P - 0 \cdot 0) \end{aligned}$$

$$6aP \hat{i} + 16aP \hat{k}$$

$$\begin{aligned} & \hat{i} (0 \cdot 0 - (-P)(8a)) \\ & - \hat{j} (16a \cdot 0 - 0 \cdot 8a) \\ & + \hat{k} (16a \cdot (-P) - 0 \cdot 0) \end{aligned}$$

$$8aP \hat{i} - 16aP \hat{k}$$

$$(6aP + 8aP) \hat{i} + (16aP - 16aP) \hat{k}$$

$$14aP \hat{i}$$

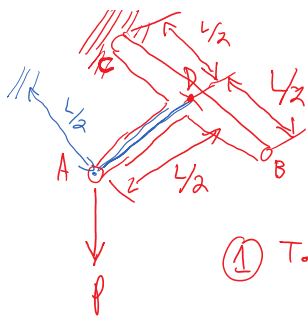
$$-T_x \hat{i} + 14aP \hat{i} = 0$$

$$\left. \begin{aligned} M_y &= 0 \\ M_z &= 0 \end{aligned} \right\} \text{No bending!}$$

$$T_x = 14aP \quad \text{Twisting Only!}$$

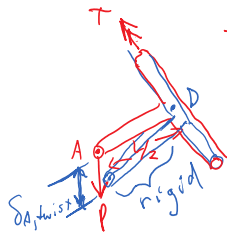
This side rotates up





- ✓ ① Twisting from C to D
- ✓ ② Bending down from C to D
- ✓ ③ Bending down from D to A

① Torque in CD



$$T = -\frac{P \cdot L}{2}$$

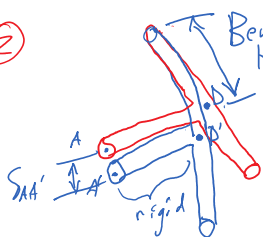
$$\phi_{CD} = \frac{T \cdot (L/2)}{G \cdot J}$$

Deflection of A will be  $-\frac{L}{2} \left( \frac{T \cdot L}{2GJ} \right)$

$$\delta_{A, twist} = -\frac{TL^2}{4GJ} = -\frac{PL^3}{8GJ}$$

Treat DA as rigid

②

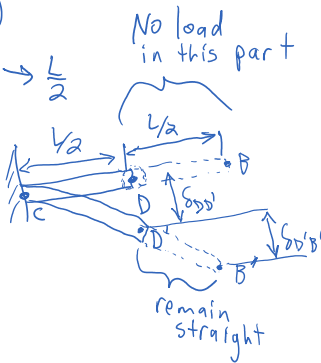


From Table  $(\delta = \frac{PL^3}{3EI})$  set  $L \rightarrow \frac{L}{2}$

$$\delta_{DD'} = -\frac{P \cdot (L/2)^3}{3EI}$$

$$\delta_{AA'} = \delta_{DD'} = -\frac{PL^3}{24EI}$$

Treat  $\begin{cases} CD \text{ as flexible} \\ DA \text{ as rigid} \\ DB \text{ is unloaded (rigid)} \end{cases}$



$$\delta_{BB'} = \delta_{DD'} + \theta_D \times \frac{L}{2}$$

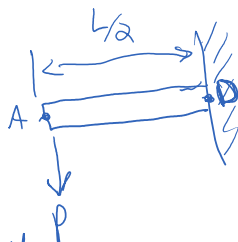
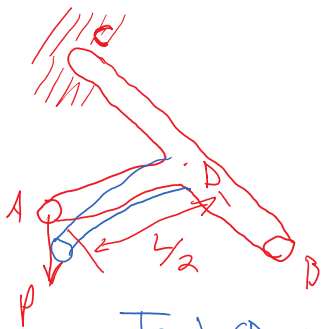
slope      length from D to B

$\theta_D$  from table is

$$\theta_B = \frac{-P \cdot L^2}{2EI} \quad \text{set } L \rightarrow \frac{L}{2}$$

$$\theta_B = \frac{-P(L/2)^2}{2EI}$$

③



$\delta_{DA} = \frac{-P(L/2)^3}{3EI}$   
 $= \frac{-PL^3}{24EI}$

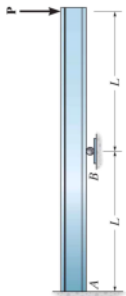
Treat CD as rigid  
 AD as flexible

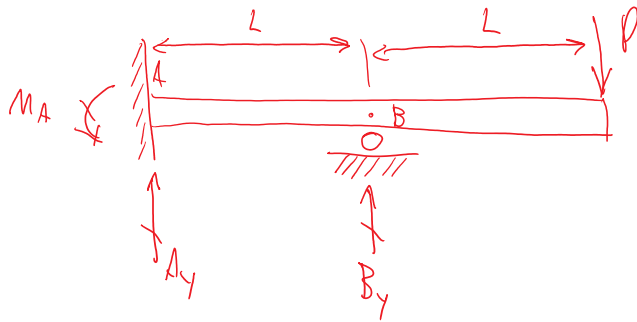
$$\delta_A = \delta_1 + \delta_2 + \delta_3$$

$$\delta_A = \frac{-PL^3}{8GJ} - \frac{PL^3}{24EI} - \frac{PL^3}{24EI}$$

$$\delta_A = -PL^3 \left( \frac{1}{8GJ} + \frac{1}{12EI} \right)$$

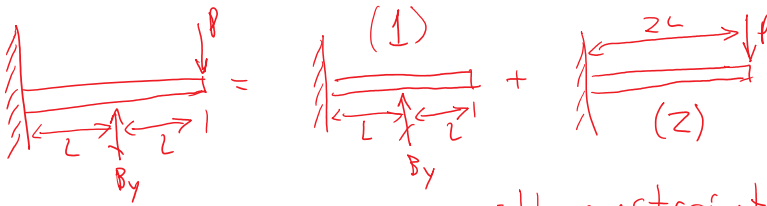
Problem 8:  
 Determine the reactions at A and B. Use deflection table.





$$(\sum M)_A = 0 \Rightarrow M_A + B_y L - 2PL = 0$$

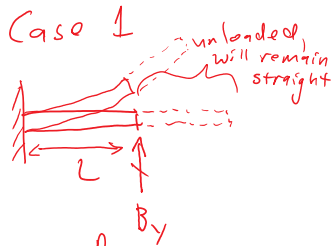
$$(\sum F_y) = 0 \Rightarrow A_y + B_y = P$$



With constraint  $y(L) = 0$

geometric compatibility condition

$$\text{Goal: } y_{1B} + y_{2B} = y(L) = 0$$

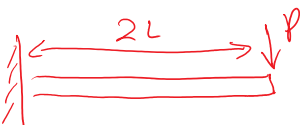


$$\delta_{\max} = \frac{PL^3}{3EI}$$

set  $P \rightarrow B_y$

$$\delta_{1B} = \frac{B_y L^3}{3EI}$$

Case 2



Take  $y(x)$   
from table

from table

$$y(x) = -\frac{Px^2}{6EI}(3L-x)$$

$$\dots \sim x^3 \text{ (from } -x)$$

Take  $y(x)$

$$y(x) = -\frac{Px^2}{6EI} (3L - x)$$

from table

$$y(x) = \frac{-Px^2}{6EI} (3(2L) - x)$$

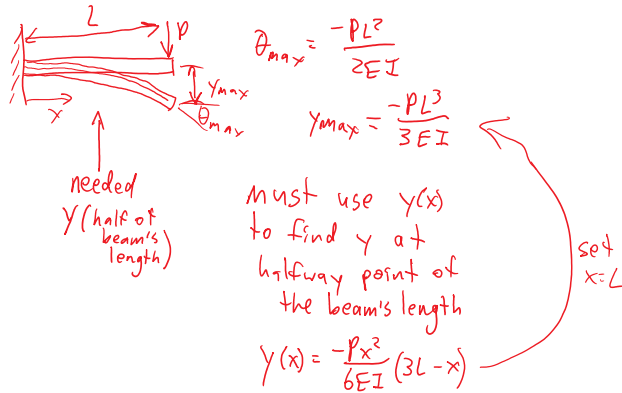
set  $L \rightarrow 2L$

and  $P \rightarrow P$

$$= \frac{-Px^2}{6EI} (6L - x)$$

Then  $x \rightarrow L$

$$y(L) = \frac{-PL^2}{6EI} 5L = -\frac{5PL^3}{6EI}$$

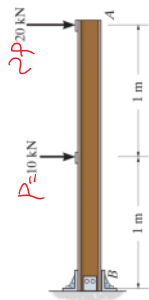


$$\left( \frac{B_y L^3}{3EI} - \frac{5PL^3}{6EI} = 0 \right) \times \frac{6EI}{L^3}$$

$$2B_y - 5P = 0$$

$$B_y = \frac{5P}{2}$$

Problem 12:  
Obtain expressions for the deflection from 0sx<1 and 1<xc<2 using ODE. Verify your results by confirming the displacement at A using the superposition method and the deflection table.



Free body diagram of the entire beam (AB):

At A:  $M_A$  (counter-clockwise),  $A_x = 0$  (horizontal),  $A_y$  (vertical, upwards).

At B:  $3P$  (vertical, upwards),  $\frac{5PL}{2}$  (counter-clockwise moment).

Equilibrium equations:

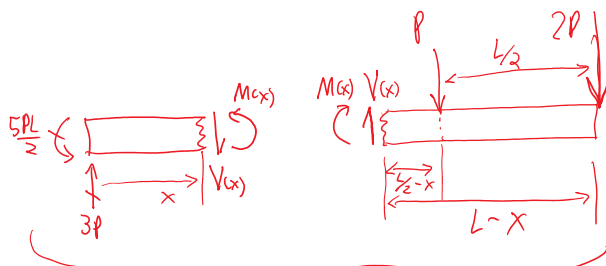
$$\sum F_y = 0 \Rightarrow -P - 2P + A_y = 0 \Rightarrow A_y = 3P$$

$$(\sum M)_A = 0 \Rightarrow -M_A - \frac{P \cdot L}{2} - 2P \cdot L = 0 \Rightarrow M_A = -\frac{5PL}{2}$$

Free body diagrams of the beam segments:

- Segment AB (length L):  $3P$  (up),  $\frac{5PL}{2}$  (CCW),  $M_A$  (CW),  $P$  (down at  $L/2$ ).
- Segment BC (length L):  $2P$  (down at A),  $3P$  (up at B),  $\frac{5PL}{2}$  (CCW at B).

Handwritten note: "either is fine once the reaction moment is known"



same cut!

Equilibrium for the left part (AB):

$$\sum M_{left} = 0 \Rightarrow M(x) + \frac{5PL}{2} - 3Px = 0 \Rightarrow M(x) = 3Px - \frac{5PL}{2}$$

Equilibrium for the right part (BC):

$$\sum M_{right} = 0 \Rightarrow -M(x) - P\left(\frac{L}{2} - x\right) - 2P(L - x) = 0$$

$$M(x) = -\frac{PL}{2} + Px - 2PL + 2Px = 3Px - 5PL$$



$$M(x) = \frac{5PL}{2}$$

$$= 3Px - \frac{5PL}{2}$$

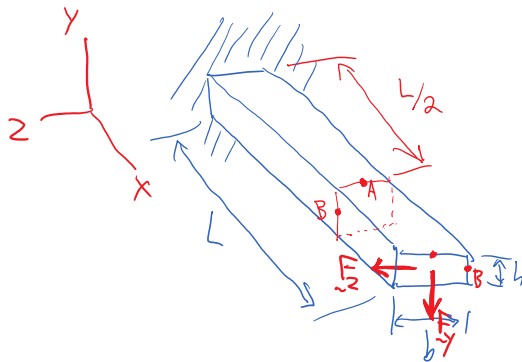
$$\text{If } M(x) > 0$$

concave up  
"smiling"

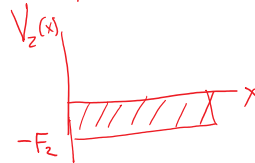
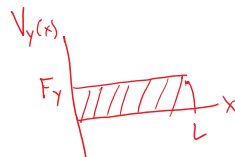
$$y''(x) = \frac{M(x)}{EI}$$

$$\text{If } M(x) < 0$$

concave down  
"frowning"



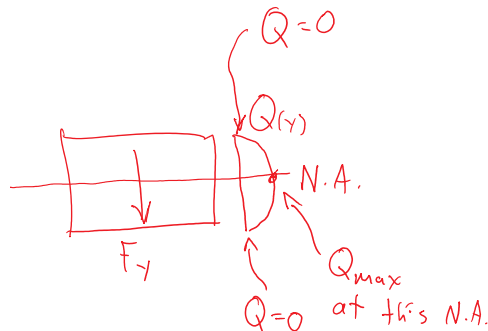
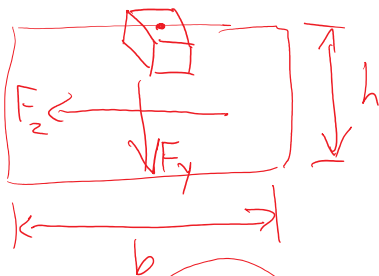
Find state of stress  
at A & B



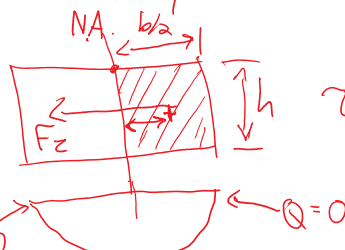
$$\vec{F}_z = F_z \hat{k}$$

$$\vec{F}_y = -F_y \hat{j}$$

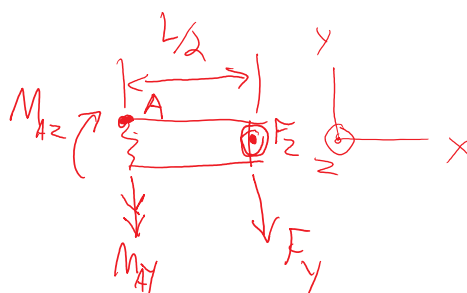
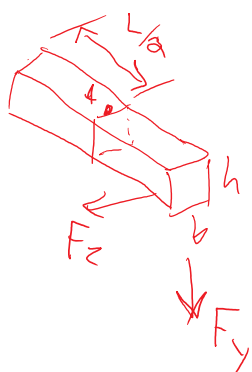
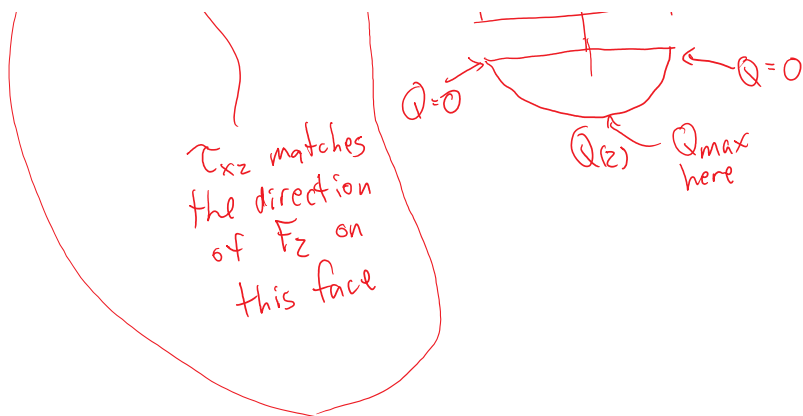
Point A



At A,  $F_y$  causes NO shear stress



$$\tau_{xz} @ A = \frac{F_z \cdot Q_{max}}{I_y \cdot t} = \frac{F_z \left( \frac{bh}{2} \right) \left( \frac{b}{4} \right)}{\left( \frac{hb^3}{12} \right) \cdot h}$$



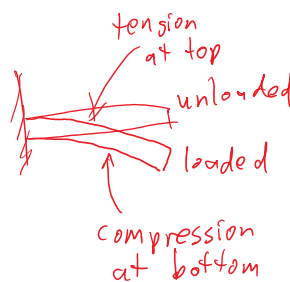
$$M_{Az} = -F_y \cdot \frac{L}{2}$$

$$|M_{Ay}| = F_z \cdot \frac{L}{2}$$

At A,  $M_{Az} = \frac{-F_y L}{2}$   
causes tension

$$\sigma_x = \frac{-M_{Az} \cdot y_{max}}{I_z}$$

$$\sigma_x = \frac{-\left(\frac{-F_y L}{2}\right)\left(\frac{h}{2}\right)}{\frac{bh^3}{12}} = \frac{3 \cdot F_y \cdot L}{bh^2}$$



At A,  $|M_{Ay}| = \frac{F_z L}{2}$  caused no flexural stress, because A is on the N.A. for the bending moment  $M_{Ay}$

